

ΘΕΜΑ Α.

A1. γ

A2. a

A3. δ

A4. δ

A5. α, Σ

β, Λ

γ, Σ

δ, Σ

ϵ, Λ

OFMA B.

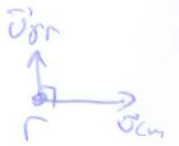
B1.

$$\vec{v}_A = \vec{v}_{cm} + \vec{v}_{rA}$$

$$v_{rA} = \omega \cdot \frac{R}{2} = \frac{v_{cm}}{2}$$

$$v_A = v_{cm} + v_{cm}$$

$$v_r = \sqrt{v_{cm}^2 + \left(\frac{v_{cm}}{2}\right)^2}$$



$$v_A = 2v_{cm} \quad (1)$$

$$v_r = \frac{v_{cm}}{2} \cdot \sqrt{5} \quad (2)$$

div (1) & (2)

$$\frac{v_r}{v_A} = \frac{\sqrt{5}}{4} \quad \text{div (ii)}$$

B2.

$$m_1 \quad \vec{v}_1 \quad m_2$$

○ → ○

$$v_2' = \frac{2m_1}{m_1 + m_2} \cdot v_1$$

$$K_2' = \frac{1}{2} m_2 v_2'^2 = \frac{1}{2} m_2 \frac{4m_1^2}{(m_1 + m_2)^2} \cdot v_1^2$$

$$\Pi_1 = \frac{K_2'}{K_1} = \frac{\frac{1}{2} \frac{4m_1^2 m_2}{(m_1 + m_2)^2} \cdot v_1^2}{\frac{1}{2} m_1 v_1^2} = \frac{4m_1 m_2}{(m_1 + m_2)^2}$$

$$m_2 \quad \vec{v}_2 \quad m_1$$

○ → ○

$$v_1' = \frac{2m_2}{m_1 + m_2} \cdot v_2 \quad K_1' = \frac{1}{2} m_1 \frac{4m_2^2}{(m_1 + m_2)^2} \cdot v_2^2$$

$$\Pi_2 = \frac{K_1'}{K_2} = \frac{\frac{1}{2} \frac{4m_1 m_2^2}{(m_1 + m_2)^2} \cdot v_2^2}{\frac{1}{2} m_2 v_2^2} = \frac{4m_1 m_2}{(m_1 + m_2)^2}$$

div (i) $\Pi_1 = \Pi_2$

B3.

Από τη σχέση Γκαλιλαιοειδούς σε ύψος H

$$\Pi = A \cdot v$$

$$\Pi = A \cdot \sqrt{2g(H-h_1)} \quad (1)$$

$$s = v \cdot t$$

$$s = \sqrt{2g(H-h_1)} \cdot \sqrt{\frac{2h_1}{g}} \quad (2)$$

$$\text{από } \frac{s}{2} = \frac{s}{2}$$

$$\frac{s}{2} = v \cdot t' \rightarrow \frac{s}{2} = \sqrt{2g(H-h_1)} \cdot \sqrt{\frac{2(h_1-h_2)}{g}} \quad (3)$$

από (2) & (3):

$$2 \sqrt{\frac{2(h_1-h_2)}{g}} = \sqrt{\frac{2h_1}{g}}$$

$$4 \cdot \frac{2(h_1-h_2)}{g} = \frac{2h_1}{g}$$

$$4h_1 - 4h_2 = h_1$$

$$h_1 = \frac{4h_2}{3} = \frac{4}{3} \cdot \frac{21H}{32} = \frac{7}{8}H$$

και από την (1)

$$\Pi = A \cdot \sqrt{2g\left(H - \frac{7}{8}H\right)}$$

$$\Pi = \frac{A}{2} \sqrt{gH} \quad \text{so } i)$$

ΘΕΜΑ Γ

Γ1. ΕΠΙΤΑΧΥΝΟΜΕΝΗ, ΔΥΝΑΜΙΣ, ΗΓΕΣΤΕΡΗ ΚΑΙ ΕΛΑΤΤΩΣΗ.

$$\Sigma F = m \cdot \alpha$$

$$F - F_L = m \cdot \alpha \Rightarrow \alpha = \frac{F - B_1 I_{en} L}{m}$$

$$\alpha = \frac{F}{m} - \frac{B_1^2 L^2 \cdot v}{m \cdot R_{\perp}}$$

$$\text{πλ } \alpha = 0 \quad v = v_{op} = 4 \text{ m/s}$$

Γ2.

ΠΡΟΣΤΑ $\Sigma F = 0$

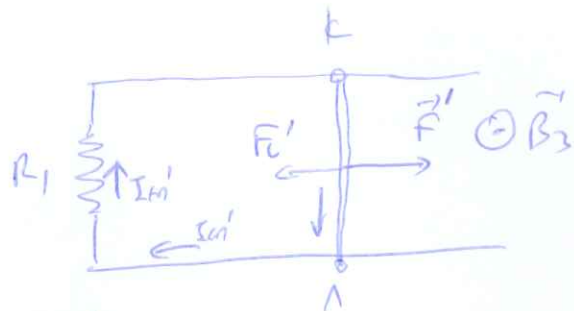
$$F' = F_L$$

$$F' = B_3 I'_{en} L$$

$$I'_{en} = \frac{\mathcal{E}_{ind}}{R_{\perp}} = \frac{B_3 \cdot v_{op} \cdot L}{R_{\perp}} = 0,8 \text{ A}$$

$$\mathcal{E}_{ind} = \frac{d\Phi}{dt} = \dots = B_3 v L$$

$$\text{άρα } F' = 9,8 \text{ N.}$$



Γ3.

$$I'_{en} = \frac{\Delta q}{\Delta t} \Rightarrow \Delta t = \frac{Q}{I'_{en}} = 0,25 \text{ sec}$$

$$Q = I'_{en}{}^2 \cdot R_{\perp} \cdot \Delta t = 0,8^2 \cdot 5 \cdot \frac{1}{4} = 0,8 \text{ Joule}$$

Γ4.

$$R_{12} = 10 \quad R'_{\perp} = R_{en} + R_{12} = 40.$$

$$\Sigma F = 0$$

$$F' = B_3 \cdot I \cdot L$$

$$F' = B_3 \cdot \frac{B_3 v_{op} L}{R'_{\perp}} \cdot L$$

$$v'_{op} = \frac{F' \cdot R'_{\perp}}{B_3^2 \cdot L^2} = \frac{98 \cdot 4}{1} = 3,2 \text{ m/s}$$

$$r_4. \quad n\alpha \quad v = v_{p'} = 3,2 \text{ m/s}$$

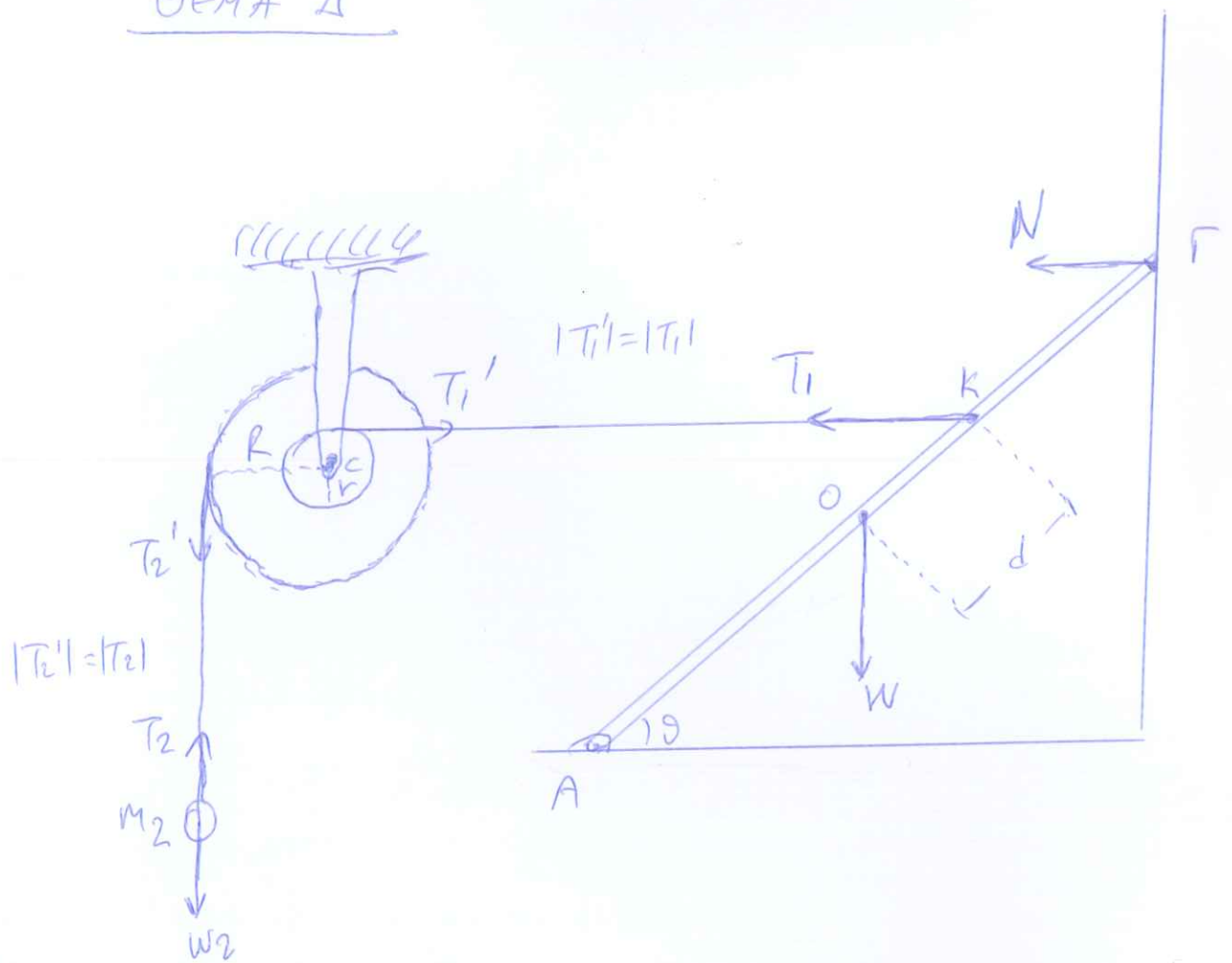
$$V_{AK} = E_{\text{emf}} - I \cdot R_{\text{KL}} = 0,8 \text{ V}$$

$$V_{K\Lambda} = -0,8 \text{ V}$$

$$\text{K1} \quad V_{AK} = I_1 \cdot R_1 \Rightarrow I_1 = 0,4 \text{ A}$$

$$V_{AK} = I_2 \cdot R_2 \Rightarrow I_2 = 0,4 \text{ A}$$

ΘΕΜΑ Δ



Δ1) Για το m_2 $w_2 = T_2$ (1)

Για το τροχαίο $\sum \tau(c) = 0 \Rightarrow T_2' \cdot R = T_1' \cdot r \Rightarrow 2T_2' = T_1'$ (2)

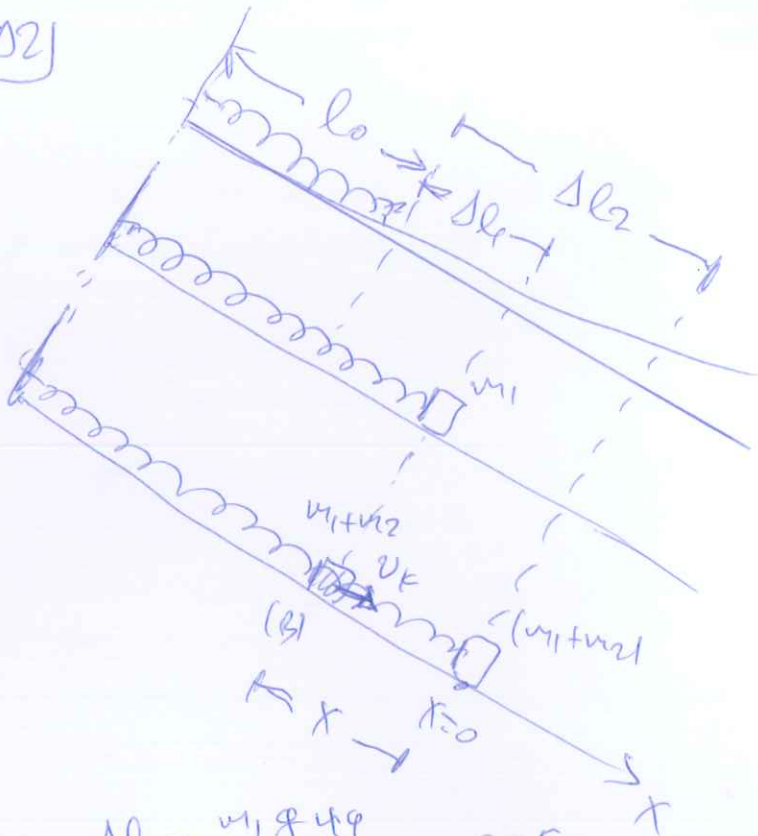
υπόκειται αλλαγή και για εξισώσεις από (1) & (2) $T_1 = 60 \text{ N}$

Για το σώμα $\sum \tau(A) = 0$

$$N \cdot l \cdot \sin \theta + T_1 \cdot \left(\frac{l}{2} + d\right) \cos \theta - W \cdot \frac{l}{2} \sin \theta = 0$$

$N = 10 \text{ N}$

02)



$$\Delta l_1 = \frac{m_1 g}{k} = 0,05 \text{ m}$$

$$\Delta l_2 = \frac{(m_1 + m_2) g}{k} = 0,2 \text{ m}$$

ADER $\mu = 20$ \rightarrow $600 \text{ g} + 200 \text{ g}$ \rightarrow 800 g \rightarrow 8 N \rightarrow B

$$E = K + U$$

$$\frac{1}{2} k A^2 = \frac{1}{2} (m_1 + m_2) v_k^2 + \frac{1}{2} k (\Delta l_2 - \Delta l_1)^2$$

$$A = 0,3 \text{ m}$$

03) $\pi \text{ a } t=0 \quad x = -0,15 \text{ m}$.

$$x = A \cos(\omega t + \varphi_0)$$

$$-0,15 = 0,34 \cos \varphi_0$$

$$4 \cos \varphi_0 = -\frac{1}{2}$$

$$4 \cos \varphi_0 = 4 \frac{7\pi}{6}$$

$$\varphi_0 = 2\pi + \frac{7\pi}{6}$$

$$\varphi_0 = 2\pi + \pi - \frac{7\pi}{6}$$

} \Rightarrow

$$\varphi_0 = \frac{7\pi}{6} \text{ rad}$$

$$\varphi_0 = \frac{11\pi}{6} \text{ rad}$$

$v > 0 \text{ a } \pi \text{ a } \dots \varphi_0 = \frac{11\pi}{6} \text{ rad}$

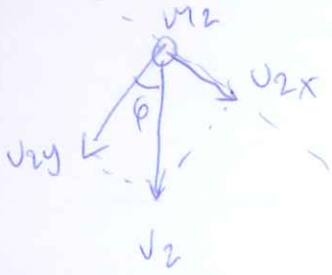
$$\omega = \sqrt{\frac{k}{m_1 + m_2}} = 5 \text{ rad/s}$$

$$x = 0,34 \cos\left(5t + \frac{11\pi}{6}\right) \quad (52)$$

4

ADME na v_2 : $K_{Apx} + U_{Apx} = K_{2cx} + U_{2cx}$

$$\frac{1}{2} m_2 v_2^2 = \frac{1}{2} m_2 v_2^2 \Rightarrow v_2 = \sqrt{2gh} = (1)$$



AD0 x'x

$$m_2 v_{2x} = (m_1 + m_2) v_K$$

$$m_2 \cdot v_2 \sin \phi = (m_1 + m_2) \cdot v_K$$

$$v_2 = 2\sqrt{3} v_K$$

Kon dio (1) $h = 0,6 \text{ m}$.

55) $p < x = +A \quad \Delta l \rightarrow \Delta l_{\text{max}}$

$$\frac{(F_{\text{el}})}{(F_{\text{elw}})} = \frac{k(\Delta l_2 + A)}{k \cdot A} = \frac{5}{3}$$